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In LiDAR, laser light is sent from a source (transmitter) and reflected from objects in the scene. The reflected light is detected by the system receiver and the time of flight (TOF) is used to develop a distance map of the objects in the scene.

a data-ved="2ahUKewjvvnvG4-s-DAXXpKQIHcOwBe4QFnoECAEQBg" href="{href}">>span>>div>>span>>What is LiDAR and How Does it Work? - Synopsys

span>>div>>synopsys : glossary : what-is-lidar

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The object-wise feature extractors project LiDAR point clouds into 2D representations and generate the object proposals using 2D networks. Then, they regress the region proposals to predict the 3D bounding boxes.

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a data-ved="2ahUKewjvvnvG4-s-DAXXpKQIHcOwBe4QFnoECAEQDQ" href="{href}">>span>>div>>span>>A Survey on Deep-Learning-Based LiDAR 3D

Object Detection for ...>>/span>>/div>>/span>>span>>div>>

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